

# PROBLEM 1

C.O.L.M. IN y DIR ↑

$$\frac{d}{dt} (IP_{y,sys}) = \sum F_y + \underbrace{\sum \dot{m}_y V_y}_{\rightarrow 0} - \sum \dot{m}_y V_y$$

$$\frac{d}{dt} (M_B \cancel{V_{By}}) = -P \sin \theta - mg + N$$

NO y

VB

$$N = P \sin \theta + mg$$

C.O.L.M. IN x DIR →

$$\frac{d}{dt} (IP_{sys,x}) = \sum F_x + \underbrace{\quad}_{\rightarrow 0} \quad \underbrace{\quad}_{\rightarrow 0}$$

$$\frac{d}{dt} [m V_G] = P \cos \theta - M_e N$$

$$m \frac{dV_G}{dt} = P \cos \theta - M_e N$$

$$\downarrow \quad \downarrow \quad \downarrow$$

$$\cancel{m} \cancel{a_G} = P \cos \theta - M_e [P \sin \theta + mg]$$

... SOLVE FOR P...

## PROBLEM 2

C.O.L.M y-DIR FOR PULLEY C ↑

$$\frac{d}{dt}(P_{y,sys}) = \sum F_y + \cancel{L_{\rightarrow 0}} - \cancel{L_{\rightarrow 0}}$$

CLOSED

$$\frac{d}{dt}(mV) = 2T_A - T_B$$

(MASSLESS)

$T_B = 2T_A$  (1)

C.O.L.M y-DIR BLOCK B ↑

$$\frac{d}{dt}(P_{sys,y}) = \sum F_y + \cancel{L_{\rightarrow 0}} - \cancel{L_{\rightarrow 0}}$$

CLOSED

$$\frac{d}{dt}(m_B[-V_B]) = T_B - m_B g$$

$$-m_B \frac{dV_B}{dt} = T_B - m_B g$$

$-m_B a_B = T_B - m_B g$  (2)

C.O.L.M x-DIR BLOCK A →

$$\frac{d}{dt}(P_{x,sys}) = \sum F_x + \cancel{L_{\rightarrow 0}} - \cancel{L_{\rightarrow 0}}$$

CLOSED

$$\frac{d}{dt}[m_A V_A] = T_A$$

$$m_A \frac{dV_A}{dt} = T_A$$

$m_A a_A = T_A$  (3)

KINEMATICS

$a_B = \frac{1}{2} a_A$  (4)

FOUR EQNS & 4 UNES

(1 → 4)

( $T_A, T_B, a_A, a_B$ )

... SOLVE

C.O.L.M BLOCK A x-DIR  $\rightarrow$

$$\frac{d}{dt} (P_{x,sys}) = \sum F_x + \underbrace{L_{in} - L_{out}}_{CLOSED}$$

$$\frac{d}{dt} (m_A v_A) = N_B \sin \theta$$

$$m_A \frac{dv_A}{dt} = N_B \sin \theta \Rightarrow m_A \overset{?}{a_A} = N_B \overset{?}{\sin \theta} \quad (1)$$

y-DIR  $\uparrow$

$$\frac{d}{dt} (P_{y,sys}) = \sum F_y$$

$$\frac{d}{dt} (m_A \overset{?}{v_{A,y}}) = N_A - m_A g - m_A g \cos \theta$$

$$0 = N_A - m_A g - m_A g \cos \theta$$

$\hookrightarrow$  CAN SOLVE FOR  $N_A \dots$

C.O.L.M BLOCK B x-DIR  $\rightarrow$



$$\frac{d}{dt} (P_{x,sys}) = \sum F_x + L_{in} - L_{out} \quad (2)$$

$$\frac{d}{dt} [m_B \overset{?}{v_{B,x}}] = m_B g \sin \theta$$

? ABSOLUTE!!

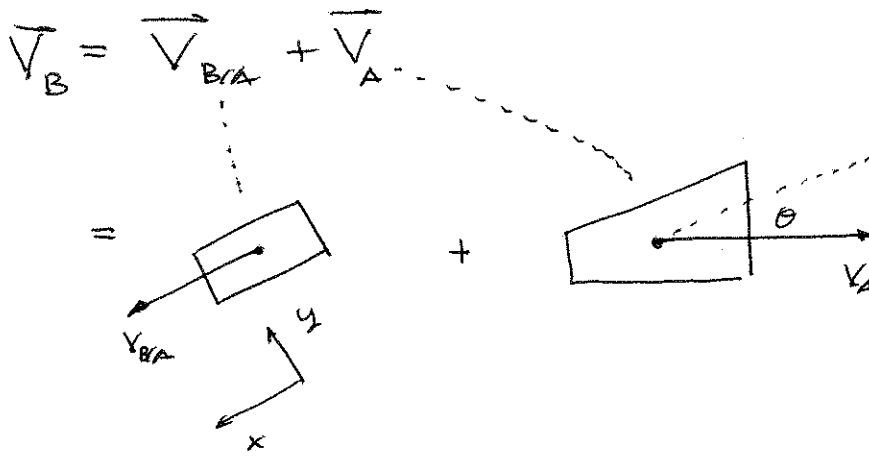
y-DIR  $\uparrow$

$$\frac{d}{dt} (P_{y,sys}) = \sum F_y + L_{in} - L_{out}$$

$$\frac{d}{dt} (m_B \overset{?}{v_{B,y}}) = N_B - m_B g \cos \theta \quad (3)$$

?

NEED RELATIVE VELOCITIES



In x

$$V_{B,x} = V_{B/A} - V_A \cos \theta$$

In y

$$V_{B,y} = 0 - V_A \sin \theta$$

(NO  $V_{B/A}$  IN y)

2 BECOMES:

$$\frac{d}{dt} [m_B (V_{B/A} - V_A \cos \theta)] = m_B g \sin \theta$$

$$m_B \frac{dV_{B/A}}{dt} - m_B \cos \theta \frac{dV_A}{dt} = m_B g \sin \theta$$

$$m_B \dot{V}_{B/A} - m_B \cos \theta \dot{V}_A = m_B g \sin \theta \quad (4)$$

3 BECOMES

$$\frac{d}{dt} (m_B (-V_A \sin \theta)) = N_B - m_B g \cos \theta$$

$$-m_B \sin \theta \frac{dV_A}{dt} = N_B - m_B g \cos \theta$$

$$-m_B \sin \theta \dot{V}_A = N_B - m_B g \cos \theta \quad (5)$$

3 EQNS (1, 4, 5), 3 UNKNOWNNS ( $N_B, \dot{V}_A, \dot{V}_{B/A}$ ) ...