PROBLEM: 4.1 Factor the following polynomial and plot its roots in the complex plane.

 $P(z) = 1 + \frac{1}{2}z^{-1} + \frac{1}{2}z^{-2} + z^{-3}$

In MATLAB see the functions called roots and zplane.

PROBLEM: 4.2 A linear time-invariant filter is described by the difference equation

$$y[n] = x[n] + x[n-1] + x[n-2] + x[n-3] = \sum_{n=0}^{3} x[n-k]$$

- - (a) What is the impulse response, h[n], of this system?

(b) Determine the system function H(z) for this system.

(c) Plot the zeros of H(z) in the complex z-plane. Hint: Remember the N-th roots of unity.

PROBLEM: 4.3 The system function of a linear time-invariant filter is given by the formula

a look at the locations of the zeros of H(z) as plotted in part (d).

 $H(z) = (1 - z^{-1})(1 - e^{j\pi/2}z^{-1})(1 - e^{-j\pi/2}z^{-1})(1 - 0.5e^{j\pi/3}z^{-1})(1 - 0.5e^{-j\pi/3}z^{-1})$

(c) Use multiplication of z-transform polynomials to find the output when the input is

(d) Plot the poles and zeros of H(z) in the z-plane.

(e) From H(z), obtain an expression for the frequency response $H(e^{j\hat{\omega}})$ of this system.

 $x[n] = \delta[n-2] + 2\delta[n-4] - \delta[n-5].$

(f) If the input is of the form $x[n] = Ae^{j\phi}e^{j\hat{\omega}n}$, for what values of frequency $\hat{\omega}$ will the output signal be zero for all n (i.e., y[n] = 0)? Find all possible frequencies in the range $-\pi \le \hat{\omega} \le \pi$. Hint: Take

We now have four ways of describing an LTI system: the difference equation with filter coefficients $\{b_k\}$; the impulse response, h[n]; the frequency response, $H(e^{j\hat{\omega}})$; and the system function, H(z). In the following,

(a) y[n] = 3(x[n] - x[n-3]).

(b)
$$h[n] = -\delta[n] - \delta[n-1] - \delta[n-2] - \delta[n-3].$$

you are given one of these representations and you must find the system function H(z).

(c) $H(e^{j\hat{\omega}}) = [2j\sin(2\hat{\omega})]e^{-j3\hat{\omega}}$.

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(d) $h[n] = \delta[n] + \delta[n-3]$.