

Name(s) _____

CM _____

ECE320: Quiz5

Consider the plant

$$G_p(s) = \frac{s+10}{s^2+10s+100}$$

Design a PID controller using *sisotool* with **complex conjugate zeros** so that

$$T_s \leq 1.0 \text{ sec}$$

$$PO \leq 15\%$$

In addition, your controller must be designed so that

$$0 \leq k_p \leq 8$$

$$0 \leq k_i \leq 70$$

$$0 \leq k_d \leq 0.3$$

Write your final values for k_p , k_i , and k_d in the space below, as well as any additional information you wish (such as the transfer function of the controller).

The form of the PID controller is $G_c(s) = \frac{k(s+z)(s+z^*)}{s}$

Note: It is better to have a controller that meets the setting time and percent overshoot requirements than no controller at all, or one that meets the k_p , k_i , and k_d requirements.