### **DeliverAl**

(Deliver-eye)

Curtis Knaack and Tyler Moore



# DeliverAl

What is it?

### What does DeliverAl try to do?

- Optimize food delivery
  - Ways to give new orders to drivers such that their path makes the most sense
  - Similar to ride sharing
  - Tries to enhance DoorDash and other similar platforms
    - Truck delivery as well



## What problem does this solve and how successful is it

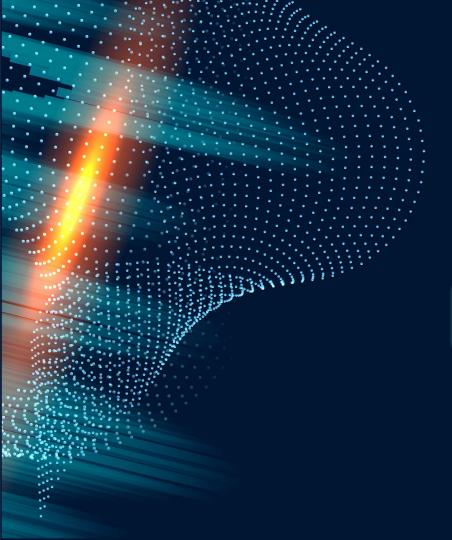
- Delivery efficiency
  - Helps with climate
  - Improves customer satisfaction
  - Driver utilization
- Quite successful overall
  - Reduces fleet size by 12%
  - Reduces distance by 13%
  - Improves utilization by 50%



## Where does this fit into the Al scene

- Competitor with bot delivery systems
- Enhances current systems instead of redesigning the solution
- Can be acquired and implemented into many existing systems
  - Potentially other delivery methods later on
- First-ever path-sharing network





# DeliverAl

Main Contributions

### Goals of the system

- Minimize distance traveled
  - Save fuel
  - Minimize environmental impact
- Minimize vehicles used
  - Concurrent deliveries
- Minimize delivery completion time
  - Still an increase



## New strategies utilized by DeliverAl

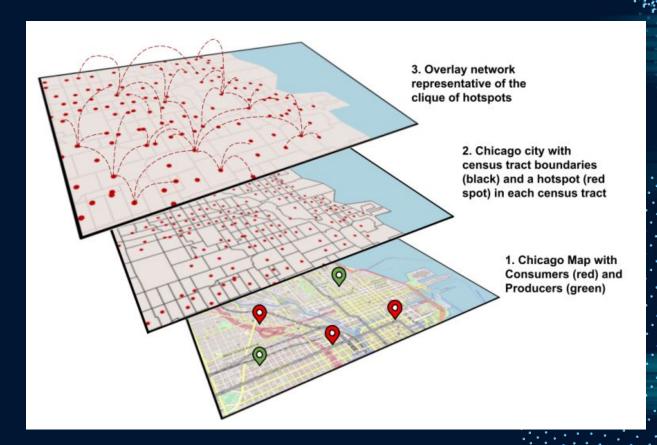
- Deliver to a central location
- "Delivery hop"
  - Synchronization issues
- Path-share
  - Utilize the same vehicle for some of the trip

#### How is this achieved?

- Determines producers/consumers
- Uses hotspots
  - Where deliveries change vehicles
- Agents trained specifically for specific hotspots



### **Overlay Network**



### **Q-Learning!**

end episode

15:

#### Algorithm 1 Q-Learning Algorithm for Training Agents

```
1: Require: learning rate \alpha \in (0, 1], discount rate \gamma \in (0, 1]
    for each h_i \in H do
 3:
        Initialize agent_i for h_i
        Initialize Q_i(s, a) arbitrarily, for all s \in S, a \in A
 4:
 5:
        Initialize policy \pi (\pi_{epsilon}/\pi_{boltzmann}) with respect to Q_i
6:
        for each episode do
 7:
           Randomly initialise initial state s_0 \neq h_i
 8:
           Select action a_0 according to policy \pi
9:
           for t = 1, 2, ... do
10:
               Choose a_t from s_t using \pi
11:
               Execute action: s_{t+1} \leftarrow a_t
12:
               Q_i(s_t, a_t) \leftarrow Q_i(s_t, a_t) + \alpha[r_i(a_t|s_t) +
                                \gamma \max_{i} Q_i(s_{t+1}, a) - Q_i(s_t, a_t)
13:
14:
               if s_{t+1} = h_i then
```

#### Conclusion

DeliverAl is very promising, but needs to be expanded beyond just one city before we see the food delivery business transformed.



### **Questions?**

