ROSE-HULMAN INSTITUTE OF TECHNOLOGY

Department of Mechanical Engineering

ES 204 Mechanical Systems

Name:

Quiz - Le 22

1. Point A has a constant velocity of 10 m/s to the right. Determine the velocity and acceleration of point B when $\theta = 30^{\circ}$. Hint: Don't you dare say the acceleration of point B is zero!

Velocity Solution:

$$\overline{v}_{\scriptscriptstyle B} = \overline{v}_{\scriptscriptstyle A} + \overline{v}_{\scriptscriptstyle B/A} = \overline{v}_{\scriptscriptstyle A} + \overline{\boldsymbol{w}}_{\scriptscriptstyle AB} \times \overline{r}_{\scriptscriptstyle B/A}$$

Expanding and equating components:

$$v_{B_{x}}\hat{i} + v_{B_{y}}\hat{j} = v_{A_{x}}\hat{i} + v_{A_{y}}\hat{j} + \mathbf{W}_{AB}\hat{k} \times \left(r_{B/A_{x}}\hat{i} + r_{B/A_{y}}\hat{j}\right)$$

$$= v_{A_{x}}\hat{i} + v_{A_{y}}\hat{j} + \mathbf{W}_{AB}r_{B/A_{x}}\hat{j} - \mathbf{W}_{AB}r_{B/A_{y}}\hat{i}$$

$$\hat{i}: v_{Bx} = v_{Ax} - \mathbf{W}_{AB} r_{B/Ay}
\hat{j}: v_{By} = v_{Ay} + \mathbf{W}_{AB} r_{B/Ax}$$
(1,2)

From the constrained motion and geometry, $v_{Bx} = v_{Ay} = 0$ and $\bar{r}_{B/A} = -0.5\hat{i} + 0.866\hat{j}$. Knowing that $v_{Ax} = 10$ allows us to solve (1,2) and get

$$\overline{\mathbf{w}}_{AB} = 11.54\hat{k} \, rad/s \quad \overline{v}_{B} = 0\hat{i} - 5.77 \, \hat{j} \, m/s$$

Acceleration Solution:

$$\overline{a}_{B} = \overline{a}_{A} + \overline{a}_{B/A} = \overline{a}_{A} + \overline{a}_{AB} \times \overline{r}_{B/A} - \mathbf{w}_{AB}^{2} \overline{r}_{B/A}$$

Expanding and equating components:

$$a_{B_{x}}\hat{i} + a_{B_{y}}\hat{j} = a_{A_{x}}\hat{i} + a_{A_{y}}\hat{j} + \mathbf{a}_{AB}\hat{k} \times (\mathbf{r}_{B/A_{x}}\hat{i} + \mathbf{r}_{B/A_{y}}\hat{j}) - \mathbf{w}_{AB}^{2} (\mathbf{r}_{B/A_{x}}\hat{i} + \mathbf{r}_{B/A_{y}}\hat{j})$$

$$= a_{A_{x}}\hat{i} + a_{A_{y}}\hat{j} + \mathbf{a}_{AB}\mathbf{r}_{B/A_{x}}\hat{j} - \mathbf{a}_{AB}\mathbf{r}_{B/A_{y}}\hat{i} - \mathbf{w}_{AB}^{2}\mathbf{r}_{B/A_{x}}\hat{i} - \mathbf{w}_{AB}^{2}\mathbf{r}_{B/A_{y}}\hat{j}$$

$$\hat{i} : a_{B_{x}} = a_{A_{x}} - \mathbf{a}_{AB}\mathbf{r}_{B/A_{y}} - \mathbf{w}_{AB}^{2}\mathbf{r}_{B/A_{x}}$$

$$\hat{j} : a_{B_{y}} = a_{A_{y}} + \mathbf{a}_{AB}\mathbf{r}_{B/A_{x}} - \mathbf{w}_{AB}^{2}\mathbf{r}_{B/A_{y}}$$

$$(3,4)$$

From the constrained motion and geometry, $a_{Bx}=a_{Ay}=0$ and $\bar{r}_{B/A}=-0.5\hat{i}+0.866\hat{j}$. Knowing that $a_{Ax}=0$ allows us to solve (3,4) and get

$$\overline{\mathbf{a}}_{AB} = 77\hat{k} \, rad/s^2 \quad \overline{a}_B = 0\hat{i} - 154\hat{j} \, m/s^2$$

All velocities and accelerations are assumed positive!

Quiz